



Approval body for construction products and types of construction

Bautechnisches Prüfamt

An institution established by the Federal and Laender Governments



European Technical Assessment

ETA-19/0501 of 22 January 2021

English translation prepared by DIBt - Original version in German language

General Part

Technical Assessment Body issuing the European Technical Assessment:

Trade name of the construction product

Product family to which the construction product belongs

Manufacturer

Manufacturing plant

This European Technical Assessment contains

This European Technical Assessment is issued in accordance with Regulation (EU) No 305/2011, on the basis of

This version replaces

Deutsches Institut für Bautechnik

fischer Superbond dynamic

Post-installed fasteners in concrete under fatigue cyclic loading

fischerwerke GmbH & Co. KG Otto-Hahn-Straße 15 79211 Denzlingen DEUTSCHLAND

fischerwerke

28 pages including 3 annexes which form an integral part of this assessment

EAD 330250-01-0601, Edition 11/2020

ETA-19/0501 issued on 30 October 2019



European Technical Assessment ETA-19/0501

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Specific Part

1 Technical description of the product

The fischer superbond dynamic is a bonded anchor consisting of a cartridge with injection mortar FIS SB or FIS SB High Speed or mortar capsule RSB, an anchor rod FIS A or RG M, a centering sleeve (only for push-through installation), a conical washer with bore, a hexagon nut with spherical contact surface and a locknut. Alternatively the hexagon nut with spherical contact surface can be replaced by a spherical disc with hexagon nut. For the sizes M20 and M24, the variant with centering sleeve, washer, hexagon nut and look nut is available as an alternative for push-through installation.

The steel element is placed into a drilled hole filled with injection mortar and is anchored via the bond between metal part, injection mortar and concrete.

The resin capsule is placed into the hole and the steel element is driven by machine with simultaneous hammering and turning. The anchor rod is anchored via the bond between steel element, chemical mortar and concrete.

The product description is given in Annex A.

2 Specification of the intended use in accordance with the applicable European Assessment Document

The performances given in Section 3 are only valid if the anchor is used in compliance with the specifications and conditions given in Annex B.

The verifications and assessment methods on which this European Technical Assessment is based lead to the assumption of a working life of the anchor of at least 50 years. The indications given on the working life cannot be interpreted as a guarantee given by the producer, but are to be regarded only as a means for choosing the right products in relation to the expected economically reasonable working life of the works.

3 Performance of the product and references to the methods used for its assessment

3.1 Mechanical resistance and stability (BWR 1)

Essential characteristic	Performance
Assessment method C: Linearized function	
Characteristic steel fatigue resistance under tension loading	See Annex C1, C3 and C4
Characteristic concrete cone, pull-out, splitting and blow out fatigue resistance under tension loading	See Annex C1, C3 and C4
Characteristic pull-out or combined pull-out /concrete cone fatigue resistance under tension loading	See Annex C1, C3 and C4
Characteristic steel fatigue resistance under shear loading	See Annex C2, C3 and C4
Characteristic concrete edge fatigue resistance under shear loading	See Annex C2, C3 and C4
Characteristic concrete pry-out fatigue resistance under shear loading	See Annex C2, C3 and C4
Characteristic steel fatigue resistance under tension and shear	See Annex C1 to C4

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Essential characteristic	Performance
Load transfer factor for tension and shear loading	See Annex C1 to C4

4 Assessment and verification of constancy of performance (AVCP) system applied, with reference to its legal base

In accordance with European Assessment Document No. 330250-01-0601, the applicable European legal act is: [96/582/EC].

The system to be applied is: 1

5 Technical details necessary for the implementation of the AVCP system, as provided for in the applicable European Assessment Document

Technical details necessary for the implementation of the AVCP system are laid down in the control plan deposited with Deutsches Institut für Bautechnik.

Issued in Berlin on 22 January 2021 by Deutsches Institut für Bautechnik

Dipl.-Ing. Beatrix Wittstock

Head of Section

beglaubigt:

Baderschneider

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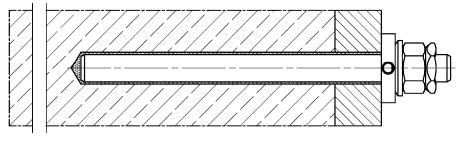


Installation conditions

fischer anchor rod FIS A or RG M with fischer injection system FIS SB

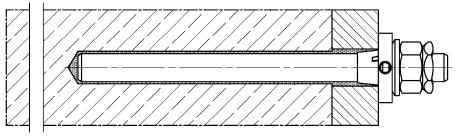
Pre-positioned installation with the necessary components (annular gap filled with mortar)

Size: M12, M16, M20, M24



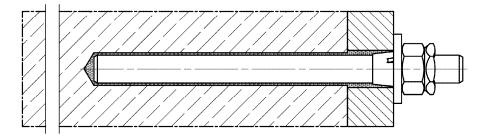
Push through installation with the necessary components (annular gap filled with mortar)

Size: M12, M16, M20, M24



Push through installation with the necessary components (annular gap filled with mortar)

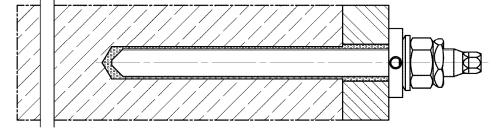
Size: M20, M24



fischer anchor rod RG M with fischer mortar capsule system RSB

Pre-positioned or push through installation with the necessary components (annular gap filled with mortar)

Size: M12, M16, M20, M24

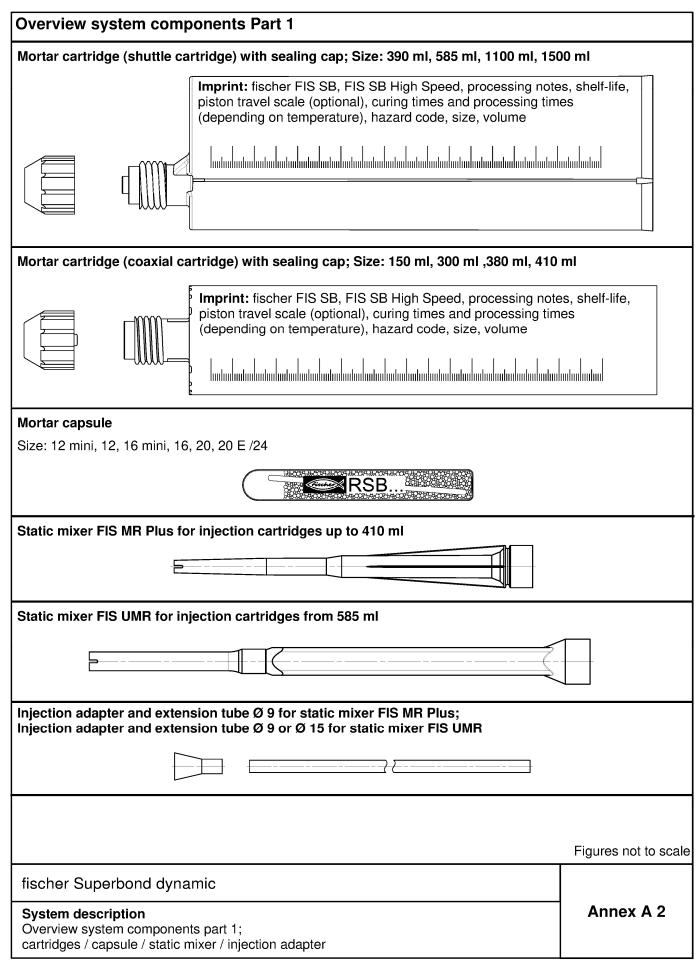


Figures not to scale

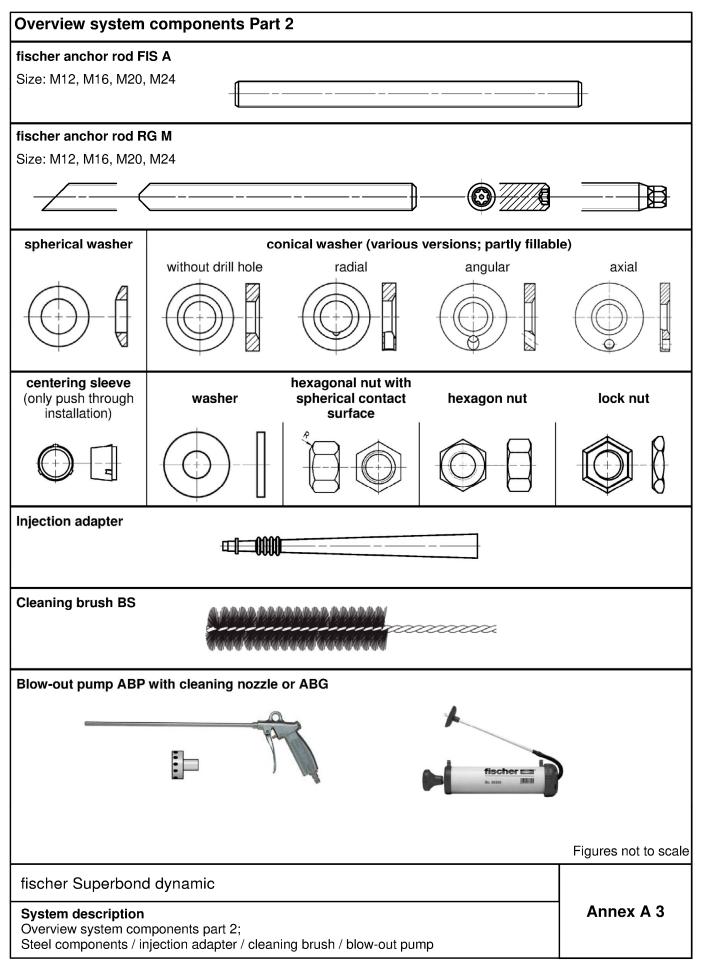
fischer Superbond dynamic

Product description Installation conditions Annex A 1











Part	Designation	Material					
1	Injection cartridge	Mortar, har	dener, filler				
2	Resin capsule	Mortar, har	dener, filler				
		Steel	Stainless steel R				
	Steel grade	zinc plated	acc. to EN 10088-1:2014 Corrosion resistance class CRC II acc. to EN 1993-1-4:2015				
3	fischer anchor rod FIS A or RG M	Property class 8.8; EN ISO 898-1:2013 zinc plated ≥ 5 μm EN ISO 4042:2018/Zn5/An (A2K) f _{uk} ≤ 1000 N/mm ²	Property class 70 EN ISO 3506-1:2009 1.4401 (M12 to M24) 1.4062 (M12 and M16) 1.4362 (M12 and M16) EN 10088-1:2014 f _{uk} ≤ 1000 N/mm ²				
4	Centering sleeve	Plastic					
5a	Washer ISO 7089:2000		1.4401; 1.4404; 1.4578; 1.4571; 1.4439; 1.4362; EN 10088-1:2014				
5b	Fillable conical washer similar to DIN 6319-G	zinc plated ≥ 5 μm, EN ISO 4042: 2018/Zn5/An (A2K)	1.4401; 1.4404; 1.4578; 1.4571; 1.4439; 1.4362; EN 10088-1:2014				
6	Spherical washer	zinc plated ≥ 5 μm, EN ISO 4042: 2018/Zn5/An (A2K)	1.4401; 1.4404; 1.4578; 1.4571; 1.4439; 1.4362; EN 10088-1:2014				
7a	Hexagon nut	Property class 8;	Property class 80				
7b	Hexagonal nut with spherical contact surface	EN ISO 898-2:2012 zinc plated ≥ 5 μm, EN ISO 4042: 2018/Zn5/An (A2K)	EN ISO 3506-1:2009 1.4401; 1.4404; 1.4578; 1.4571; 1.4439; 1.4362; EN 10088-1:2014				
8	Lock nut	zinc plated ≥ 5 μm, EN ISO 4042: 2018/Zn5/An (A2K)	1.4401; 1.4404; 1.4578; 1.4571; 1.4439; 1.4362; EN 10088-1:2014				

fischer Superbond dynamic	
Product description	Annex A 4
Materials	



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Specifications of intended use (part 1) **Table B1.1:** Overview use and performance categories injection motar system FIS SB with fischer anchor rod FIS A or fischer anchor rod RG M M12 - M24 M20 + M24Hammer drilling with standard drill bit Hammer drilling with hollow drill bit Nominal drill bit diameter (do) 14 mm to 28 mm (fischer "FHD", Heller "Duster Expert"; Bosch "Speed Clean"; Hilti "TE-CD, TE-YD"; DreBo "D-Plus"; DreBo "D-Max") Diamond drilling no performance assessed uncracked concrete Steel, zinc plated: Stainless steel R: Fatigue load, in M12 and M16 M12, M16, M20 and M24 cracked concrete Design method I n = 1 to $n = \infty$ acc. to EOTA TR 061:2020-08 Design method II n = ∞ acc. to EOTA TR 061:2020-08 Use I1 dry or wet concrete M12, M16, M20 and M24 category D3 Installation direction Downwards, horizontal and upwards (overhead) installation pre-positioned or push through installation Installation method $T_{i,min} = -15 \, ^{\circ}\text{C} \text{ to } T_{i,max} = +40 \, ^{\circ}\text{C}$ FIS SB: Installation temperature FIS SB High Speed: $T_{i,min} = -20$ °C to $T_{i,max} = +40$ °C **Temperature** (max. short term temperature +40 °C; -40 °C to +40 °C range I: max. long term temperature +24 °C) In-service temperature Temperature (max. short term temperature +80 °C; -40 °C to +80 °C range II: max. long term temperature +50 °C) fischer Superbond dynamic Annex B 1 Intended use Specifications injection motar system FIS SB (part 1)



Specifications of intended use (part 2) Table B2.1: Overview use and performance categories resin capsule system **RSB** with fischer anchor rod RG M Hammer drilling with standard drill Hammer drilling Nominal drill bit diameter (d₀) with hollow drill bit 14 mm to 28 mm (fischer "FHD", Heller "Duster Expert"; Bosch "Speed Clean"; Hilti "TE-CD, TE-YD": DreBo "D-Plus"; DreBo "D-Max") Nominal drill bit diameter (d₀) Diamond drilling 18 mm to 28 mm uncracked concrete Steel, zinc plated: Stainless steel R: Fatigue load, in M12 and M16 M12, M16, M20 and M24 cracked concrete Design method I n = 1 to $n = \infty$ acc. to TR061:2020-08 Design method II n = ∞ acc. to TR061:2020-08 Use M12, M16, M20 and M24 11 dry or wet concrete category D3Installation direction Downward, horizontal and upwards (overhead) installation pre-positioned or push through installation Installation method Installation temperature $T_{i,min} = -30$ °C to $T_{i,max} = +40$ °C (max. short term temperature +40 °C; Temperature -40 °C to +40 °C max. long term temperature +24 °C) range I: In-service temperature (max. short term temperature +80 °C; Temperature -40 °C to +80 °C range II: max. long term temperature +50 °C) fischer Superbond dynamic Annex B 2 Intended use Specifications resin capsule system RSB (part 2)



Specifications of intended use (part 3)

Base materials:

 Compacted reinforced or unreinforced normal weight concrete without fibers of strength classes C20/25 to C50/60 according to EN 206:2013+A1:2016

Use conditions (Environmental conditions):

- Structures subject to dry internal conditions (zinc plated steel, stainless steel R).
- For all other conditions according to EN1993-1-4:2015 corresponding to corrosion resistance classes to Annex A 4 table A4.1.

Design:

- Anchorages have to be designed by a responsible engineer with experience of concrete anchor design.
- Verifiable calculation notes and drawings are to be prepared taking account of the loads to be anchored.
 The position of the anchor is indicated on the design drawings (e. g. position of the anchor relative to
 reinforcement or to supports, etc.).
- · Anchorages have to be designed in accordance with:
 - EN 1992-4:2018 or
 - EOTA Technical Report TR 061 "Design method for fasteners in concrete under fatigue cyclic loading", Edition August 2020
- Static and quasi static loading see ETA-12/0258:2020
- · Anchorages shall be positioned outside of critical regions (e.g. plastic hinges) of the concrete structure
- Fastenings in stand-off installation or with a grout layer are not covered by this European Technical Assessment (ETA)

Installation:

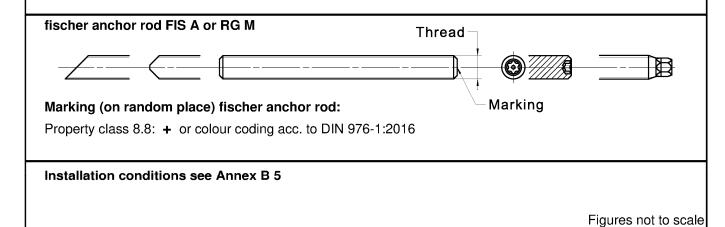
- Anchor installation is to be carried out by appropriately qualified personnel and under the supervision of the person responsible for technical matters of the site
- · In case of aborted hole: The hole shall be filled with mortar
- Anchorage depth should be marked and adhered to on installation
- If only tension loads are involved in the application, the annular gap does not need to be filled
- · Overhead installation is allowed

fischer Superbond dynamic	
Intended use Specifications (part 3)	Annex B 3



Table B4.1: Installation parameters for fischer anchor rods in combination with injection mortar system FIS SB

fischer anchor ro	ds		Thread	M12	M16	M20	M24	
Material					ed steel or s steel R	stainless	s steel R	
Width across flats		SW		19	24	30	36	
Nominal drill hole o	liameter	d ₀		14	18	24	28	
Drill hole depth		h ₀			h ₀ =	h _{ef}		
Effective embedme	ant donth	$h_{\text{ef, min}}$		70	80	90	96	
Ellective embedine	ен аери	h _{ef, max}		240	320	400	480	
Minimum spacing and minimum edge distance		Smin = Cmin	[mm]	55	65	85	105	
Diameter of the	pre-positioned installation	df	[,,,,,	14-16	18-20	22-26	26-30	
clearance hole of the fixture	push through installation	df		15-16	19-20	25-26	29-30	
Fixture thickness		t _{fix,min}		12	16	20	24	
rixture triickness		$t_{\text{fix,max}}$		200				
Minimum thickness member	of concrete	h _{min}		h _{ef} + 30	h _{ef} + 2d ₀	h _{ef} + 2d ₀	h _{ef} + 2d ₀	
Installation with c	onical washer							
Protrusion anchor i RG M without hexa		h _{p,min}	[mana]	25 + t _{fix}	30 + t _{fix}	36 + t _{fix}	43 + t _{fix}	
Protrusion anchor rod RG M (with hexagon head)		h _{p,min}	[mm]	32 + t _{fix}	38 + t _{fix}	43 + t _{fix}		
Installation with w	vasher (M20 + M	24)						
Protrusion anchor rod FIS A or RG M without hexagon head		h _{p2,min}	[mm]			27 + t _{fix}	32 + t _{fix}	
Protrusion anchor i (with hexagon head		h _{p2,min}	[mm]			34 + t _{fix}		
Required installation	n torque	T _{inst}	[Nm]	40	60	120	150	



fischer Superbond dynamic

Intended use

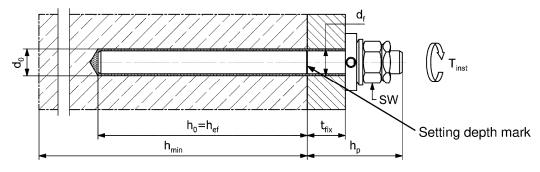
Installation parameters fischer anchor rods FIS A and RG M in combination with injection mortar system FIS SB $\,$

Annex B 4

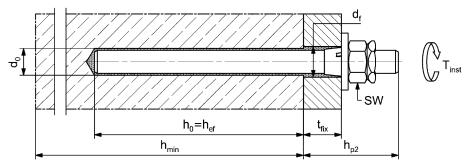


Installation conditions FIS A or RG M with conical washer or washer

Installation conditions FIS A or RG M with conical washer



Installation conditions FIS A or RG M with washer



Installation conditions for RG M see Annex B 6

Figures not to scale

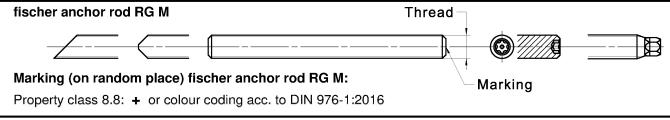
Intended use
Installation conditions FIS A or RG M with conical washer or washer

Annex B 5

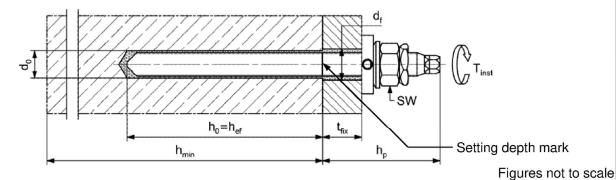


Table B6.1:	Installation parameters for fischer anchor rods RG M in combination with
	resin capsule system RSB

fischer anchor ro	RG M		Thread	M12	M16	M20	M24	
Material				zinc plated steel or stainless steel R		stainles	stainless steel R	
Width across flats		SW		19	24	30	36	
Nominal drill hole o	liameter	d ₀		14	18	25	28	
Drill hole depth		h ₀			h ₀ =	= h _{ef}		
		h _{ef,1}		75	95			
Effective embedme	ent depth	h _{ef,2}		110	125	170	210	
	•	h _{ef,3}		150	190	210		
Minimum spacing and minimum edge distance		Smin = Cmin	[mm]	55	65	85	105	
Diameter of the clearance hole of	pre-positioned installation	d _f		14-16	18-20	22-26	26-30	
the fixture	push through installation	df		15-16	19-20	26	29-30	
Et i i i italia i i i		t _{fix,min}		12	16	20	24	
Fixture thickness	-	t _{fix,max}			20	00		
Minimum thickness of concrete		h _{min}		h _{ef} + 30	h _{ef} + 2d ₀	h _{ef} + 2d ₀	h _{ef} + 2d ₀	
Installation with c	onical washer		'		1	1		
Protrusion anchor rod RG M hp,min				32 + t _{fix}	38 + t _{fix}	43 + t _{fix}		
Protrusion anchor rod RG M without hexagon head hp,mir			[mm]				43 + t _{fix}	
Required installation	n torque	T _{inst}	[Nm]	40	60	120	150	



Installation conditions:



fischer Superbond dynamic

Intended use

Installation parameters fischer anchor rod RG M in combination with resin capsule system RSB

Annex B 6

English translation prepared by DIBt



Table B7.	1:	Dimer	sion of resir	capsule RS	SB			
Resin caps	ule RS	В	12 mini	12	16 mini	16	20	20 E / 24
Capsule de diameter de 12,5 16,5 23,0							3,0	
Capsule length	LP	[mm]	72	97	72	95	160	190



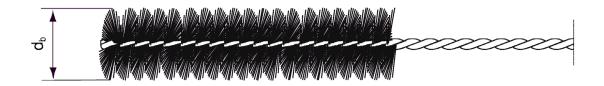
 Table B7.2:
 Assignment of resin capsule RSB to fischer anchor rod RG M

Anchor rod RG M			M12	M16	M20	M24
Effective anchorage depth	h _{ef,1}	[mm]	75	95		
Related capsule RSB		[-]	12 mini	16 mini		
Effective anchorage depth	h _{ef,2}	[mm]	110	125	170	210
Related capsule RSB		[-]	12	16	20	20 E / 24
Effective anchorage depth	h _{ef,3}	[mm]	150	190	210	
Related capsule RSB		[-]	2x 12 mini	2x 16 mini	20 E / 24	

Table B7.3: Parameters of the cleaning brush BS (steel brush with steel bristles)

The size of the cleaning brush refers to the drill hole diameter

Nominal drill hole diameter	d ₀	[mm]	14	18	24	25	28
Steel brush diameter	d₀	[mm]	16	20	26	27	30



fischer Superbond dynamic	
Intended use	Annex B 7
Dimensions of the capsules; Assignment of the capsule to the anchor rod RG M;	
Cleaning brush (steel brush)	



Table B8.1: Maximum processing time of the mortar and minimum curing time

During the curing time of the mortar the concrete temperature may not fall below the listed minimum temperature. Minimal cartridge temperature +5 °C; minimal resin capsule temperature -15 °C

Temperature at	Maximum pro tw	Minimum curing time			
anchoring base [°C]	FIS SB	FIS SB High Speed	FIS SB	FIS SB High Speed	RSB
-30 to -20					120 h
> -20 to -15		60 min		24 h	48 h
>-15 to -10	60 min	30 min	36 h	8 h	30 h
>-10 to -5	30 min	15 min	24 h	3 h	16 h
> -5 to 0	20 min	10 min	8 h	2 h	10 h
> 0 to 5	13 min	5 min	4 h	1 h	45 min
> 5 to 10	9 min	3 min	2 h	45 min	30 min
> 10 to 20	5 min	2 min	1 h	30 min	20 min
> 20 to 30	4 min	1 min	45 min	15 min	5 min
> 30 to 40	2 min		30 min		3 min

fischer Superbond dynamic

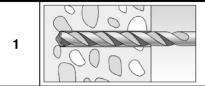
Intended use
Processing time and curing time

Annex B 8



Installation instructions part 1; injection mortar system FIS SB

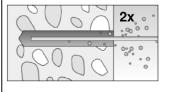
Drilling and cleaning the hole (hammer drilling with standard drill bit)



Drill the hole.

Nominal drill hole diameter d_0 and drill hole depth h_0 see $table\ B4.1$





Clean the drill hole:

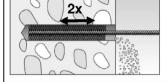
Blow out the drill hole twice, with oil free compressed air ($p \ge 6$ bar)

In uncracked concrete the use of the manual blow-out pump ABG is possible (Installation parameters:

 $d_0 < 18 \text{ mm} \text{ and } h_{ef} < 10d)$



3

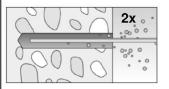


Brush the drill hole twice.

For deep holes use an extension.

Corresponding brushes see table B7.3

4



Clean the drill hole:

Blow out the drill hole twice, with oil free compressed air ($p \ge 6$ bar)

In uncracked concrete the use of the manual blow-out pump ABG is possible (Installation parameters:

 $\dot{d}_0 < 18$ mm and $h_{ef} < 10d$)



Go to step 5 (Annex B 10)

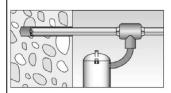
Drilling and cleaning the hole (hammer drilling with hollow drill bit)

1



Check a suitable hollow drill (see **table B1.1**) for correct operation of the dust extraction

2



Use a suitable dust extraction system, e.g. fischer FVC 35 M or a comparable dust extraction system with equivalent performance data.

Drill the hole with hollow drill bit. The dust extraction system has to extract the drill dust nonstop during the drilling process and must be adjusted to maximum power.

Nominal drill hole diameter d₀ and drill hole depth h₀ see table B4.1

Go to step 5 (Annex B 10)

fischer Superbond dynamic

Intended use

Installation instructions part 1; injection motar system FIS SB

Annex B 9



Preparing the cartridge Remove the sealing cap Screw on the static mixer (the spiral in the static mixer must be clearly visible) Place the cartridge into the dispenser Extrude approximately 10 cm of material out until the resin is evenly grey in colour. Do not use mortar that is not uniformly grey

Go to step 8 (pre-positioned installation Annex B 11 or push through installation Annex B 12)

fischer Superbond dynamic	
Intended use Installation instructions part 2; injection motar system FIS SB	Annex B 10

Intended use



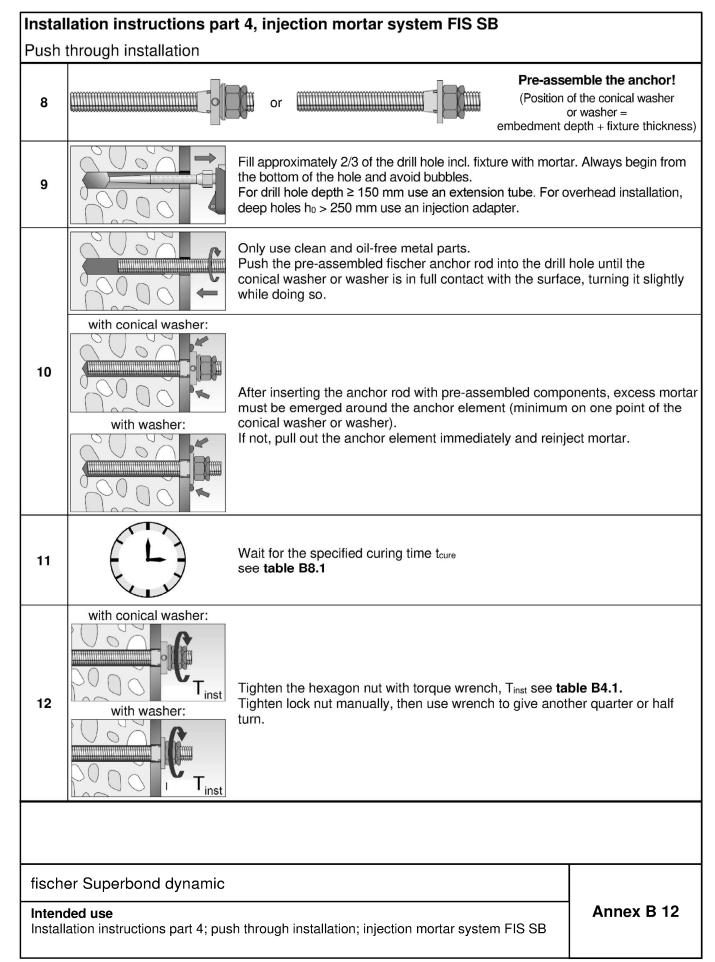
Installation instructions part 3, injection mortar system FIS SB Pre-positioned installation Fill approximately 2/3 of the drill hole with mortar. Always begin from the bottom of the hole and avoid bubbles. 8 For drill hole depth ≥ 150 mm use an extension tube. For overhead installation, deep holes $h_0 > 250$ mm use an injection adapter. Only use clean and oil-free metal parts. Mark the setting depth of the anchor rod. Push the fischer anchor rod down to the bottom of the hole, turning it slightly while doing so. After inserting the anchor rod, excess mortar must be emerged around the anchor element. If not, pull out the anchor element immediately and reinject 9 mortar. For overhead installations support the anchor rod with wedges (e.g. fischer centering wedges) until the mortar begins to harden. Wait for the specified curing time tcure 10 see table B8.1 Attach the component and install the washer and nuts - without centering 11 Tighten the hexagon nut with torque wrench, Tinst see table B4.1. Tighten lock nut manually, then use wrench to give another quarter or half The gap between anchor and fixture (annular clearance) has to be filled with mortar (FIS SB or FIS SB High Speed) via the fillable conical washer. 12 If only tension loads are involved in the application, the annular gap does not necessarily have to be filled. fischer Superbond dynamic

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Installation instructions part 3; pre-positioned installation; injection mortar system FIS SB

Annex B 11



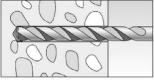




Installation instructions part 5; resin capsule RSB

Drilling and cleaning the hole (hammer drilling with standard drill bit)

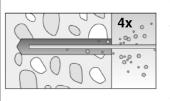
1



Drill the hole.

Nominal drill hole diameter \textbf{d}_0 and drill hole depth \textbf{h}_0 see table B6.1

2



Clean the drill hole:

Blow out the drill hole four times, with oil free compressed air ($p \ge 6$ bar)

In uncracked concrete the use of the manual blow-out pump ABG is possible (Installation parameters:

 $d_0 < 18 \text{ mm} \text{ and } h_{ef} < 10d)$



Go to step 6 (pre-positioned installation Annex B 15 or push through installation Annex B 16)

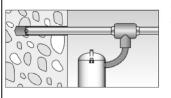
Drilling and cleaning the hole (hammer drilling with hollow drill bit)

1



Check a suitable hollow drill (see **table B2.1**) for correct operation of the dust extraction

2



Use a suitable dust extraction system, e.g. fischer FVC 35 M or a comparable dust extraction system with equivalent performance data.

Drill the hole with hollow drill bit. The dust extraction system has to extract the drill dust nonstop during the drilling process and must be adjusted to maximum power.

Nominal drill hole diameter do and drill hole depth ho see table B6.1

Go to step 6 (pre-positioned installation Annex B 15 or push through installation Annex B 16)

fischer Superbond dynamic

Intended use

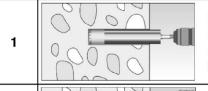
Installation instructions part 5; resin capsule RSB

Annex B 13

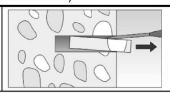


Installation instructions part 6; resin capsule RSB

Drilling and cleaning the hole (wet drilling with diamond drill bit)



Drill the hole. Drill hole diameter d_0 and nominal drill hole depth h_0 see table B6.1



Break the drill core and remove it

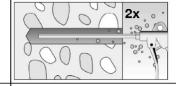


3

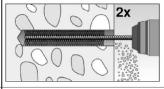
4

5

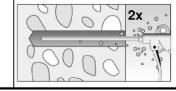
Flush the drill hole, until clear water emerges from the drill hole.



Blow out the drill hole twice, using oil-free compressed air (p > 6 bar)



Brush the drill hole twice using a power drill. Corresponding brushes see **table B7.3**



Blow out the drill hole twice, using oil-free compressed air (p > 6 bar)

Go to step 6 (pre-positioned installation Annex B 15 or push through installation Annex B 16)

fischer Superbond dynamic

Intended use

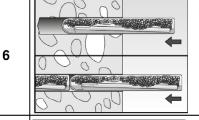
Installation instructions part 6; resin capsule RSB

Annex B 14



Installation instructions part 7; resin capsule RSB

Pre-positioned installation fischer anchor rod RG M



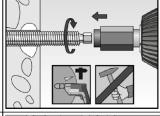
Insert the resin capsule into the drill hole by hand.

Suitable resin capsule RSB or RSB mini see table B7.2.



Depending on the metal part, use a suitable setting tool / adapter





Only use clean and grease-free metal parts. Drive the fischer anchor rod RG M into the capsule using suitable adapter and hammer drill set on rotary hammer action. Stop when the metal part reaches the bottom of the hole and the correct embedment depth is reached.





When the correct embedment depth is reached, excess mortar must emerge from the mouth of the drill hole.

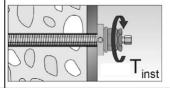
If not, the metal part must be pulled out directly and another resin capsule must be pushed into the drill hole. Setting process (Step 7) must be repeated

9



Wait for the specified curing time tcure see table B8.1

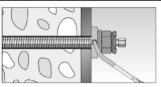




Attach the component and install the washer and nuts - without centering sleeve.

Tighten the hexagon nut with torque wrench, T_{inst} see **table B6.1**. Tighten lock nut manually, then use wrench to give another quarter or half turn

11



The gap between anchor and fixture (annular clearance) has to be filled with mortar (FIS SB or FIS SB High Speed) via the fillable conical washer. If only tension loads are involved in the application, the annular gap does not necessarily have to be filled.

fischer Superbond dynamic

Intended use

Installation instructions part 7; resin capsule RSB, pre-positioned installation

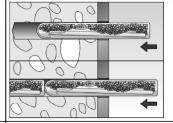
Annex B 15



Installation instructions part 8; resin capsule RSB

Push through installation fischer anchor rod RG M



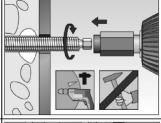


Insert the resin capsule through the fixture into the drill hole by hand. Suitable resin capsule RSB or RSB mini see table B7.2.



Depending on the metal part, use a suitable setting tool / adapter





Only use clean and grease-free metal parts. Drive the fischer anchor rod RG M into the capsule using suitable adapter and hammer drill set on rotary hammer action. Stop when the metal part reaches the bottom of the hole and the correct embedment depth is reached.





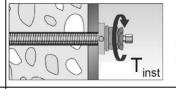
When the correct embedment depth is reached, excess mortar must be visible in the mounting part. If not, the metal part must be pulled out directly and another resin capsule must be pushed into the drill hole. Setting process (Step 7) must be repeated

9



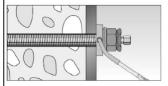
Wait for the specified curing time t_{cure} see **table B8.1**

10



Install the washer and nuts - without centering sleeve. Tighten the hexagon nut with torque wrench, T_{inst} see **table B6.1**. Tighten lock nut manually, then use wrench to give another quarter or half turn.

11



The gap between anchor and fixture (annular clearance) has to be filled with mortar (FIS SB or FIS SB High Speed) via the fillable conical washer. If only tension loads are involved in the application, the annular gap does not necessarily have to be filled.

fischer Superbond dynamic

Intended use

Installation instructions part 8; resin capsule RSB, push through installation

Annex B 16



Table C1.1: Essential characteristics under tension fatigue load for FIS SB / RSB; Design method I according to TR 061								
Required evidence								
Number of load cycles (n)								
n ≤ 10 ⁴	$10^4 < n \le 5 \cdot 10^6$	$5 \cdot 10^6 < n \le 10^8$	n > 10 ⁸					
		n load capacity						
	Characteristic steel fatigue resistance (zinc plated steel 8.8) ΔN _{Rk,s,0,n} (8.8) [kN]							
0,75·N _{Rk,s,(8.8)} ·0,33	$0,75 \cdot N_{Rk,s,(8.8)} \cdot 10^{(-0,12 \cdot \log(n))}$ $\leq 0,75 \cdot N_{Rk,s,(8.8)} \cdot 0,33$	0,75·N _{Rk,s,(8.8)} ·10 ^{(-0,438-0,057·log(n))}	0,75·N _{Rk,s,(8.8)} ·0,12					
Chara	_	ance (stainless steel R, property cla s,o,n (R-70) [kN]	ss 70)					
0,75·N _{Rk,s,(R-70)} ·0,33	$0,75 \cdot N_{Rk,s,(R-70)} \cdot 10^{(-0,16-0,09 \cdot \log n)}$	$ 0,75 \cdot N_{Rk,s,(R\text{-}70)} \cdot 10^{(-0,469-0,043 \cdot \log(n))} $	0,75·N _{Rk,s,(R-70)} ·0,15					
Characteristic con		stance, concrete failure and pull out,	in uncracked and					
		trength in uncracked concrete						
		n,ucr,0,n [N/mm²]	_					
τ _{Rk,ucr} · 0,575	$ au_{Rk,ucr} \cdot 10^{(-0,06 \cdot \log(n))}$	$ au_{ m Rk,ucr} \cdot 10^{(-0,207-0,029 \cdot \log(n))}$	τ _{Rk,ucr} · 0,35					
		strength in cracked concrete p,cr,0,n [N/mm²]						
τ _{Rk,cr} · 0,575	$ au_{Rk,cr} \cdot 0,575 $							
Characteristic fatigue resistance for concrete cone and concrete splitting								
	_	ue resistance in uncracked concrete s,c/sp,ucr,0,n [kN]	•					
N _{Rk,c/sp,ucr} · 0,66	N _{Rk,c/sp,ucr} ·1,1·	$n^{-0.055} \ge N_{\text{Rk,c/sp,ucr}} \cdot 0.50$	N _{Rk,c/sp,ucr} · 0,50					
		igue resistance in cracked concrete k,c/sp,cr,0,n [kN]						
N _{Rk,c/sp,cr} · 0,66	N _{Rk,c/sp,cr} ·1,1·	N _{Rk,c/sp,cr} · 0,50						
Exponents and load-transfer factor								
Exponent for combined		6 M20						
	M12 M1	M24						
$\alpha_{s = \alpha_{sn}} [-] $ Load-transfer factor	0,5	0,7						
ΨFN [-]		0,5						
N _{Rk,s} , τ _{Rk,ucr} , τ _{Rk,cr} s	ee ETA-12/0258:2020, for τ _{RI} see ETA-12/0258:2020 or EN	x (M24-R-70) ≤ 0,85 · τ _{Rk} (M20-R-70)						
fischer Superbond dynamic								
Performance Essential characteristi Design method I acco	Annex C 1							



Table C2.1: Essential characteristic under shear fatigue load for FIS SB / RSB; Design method I according to TR 061							
Required evidence							
Number of load cycles (n)							
n ≤ 10 ⁴		10	$10^4 < n \le 5 \cdot 10^6 \qquad \qquad 5 \cdot 10^6 < n \le 10^8$				
Shear load capacity							
Characteristic steel fatigue resistance (zinc plated steel 8.8) ΔV _{Rk,s,0,n} (8.8) [kN]							
$V_{Rk,s,(8.8)}\cdot c$),23	$ \begin{array}{ c c c c c c } \hline V_{Rk,s,(8.8)} \cdot 10^{(-0.147 \cdot \log(n))} & & V_{Rk,s,(8.8)} \cdot 10^{(-0.573 - 0.068 \cdot \log(n))} \\ & \leq V_{Rk,s,(8.8)} \cdot 0.23 & \geq V_{Rk,s,(8.8)} \cdot 0.08 \\ \hline \end{array} $				V _{Rk,s,(8.8)} · 0,08	
C	Characterist	ic steel fa	tigue resistance (sta ΔV _{Rk,s,0,n} (R-70)	│ nless steel R, property cla ſkNl	ss 7	0)	
				[]			
$V_{Rk,s,(R-70)}$. (0,31	V _{Rk,s,(R-70)}	$0.10^{(-0.042-0.118 \cdot \log(n))}$	$V_{\text{Rk,s,(R-70)}} \cdot 10^{(-0.461-0.056 \cdot \log n)}$	g(n))	V _{Rk,s,(R-70)} · 0,12	
Charac	cteristic co	ncrete pry	out fatigue resistand ΔV _{Rk,cp,0,n} [kl	e in cracked and uncracke	ed co	oncrete	
			ΔVHK,cp,u,n [NI	1			
V _{Rk,cp} · 0,5	$V_{Rk,cp} \cdot 0,574$ $V_{Rk,cp} \cdot 1,2 \cdot n^{-0,08} \ge V_{Rk,cp} \cdot 0,50$						
Chara	acteristic co	oncrete ed	lge fatigue resistance	in cracked and uncracked	d cor	ncrete	
			ΔV _{Rk,c,0,n} [kN]			
V _{Rk,c} · 0,5	$V_{Rk,c} \cdot 1, 2 \cdot n^{-0.08} \ge V_{Rk,c} \cdot 0,50$					V _{Rk,c} · 0,50	
			Exponents, load-tran	sfer factor			
Exponent for comb	oined load, s	teel failure)				
	M12		M16	M20		M24	
$\alpha_s = \alpha_{sn}$ [-]	0,5			0,7			
	oined load, v	erification	regarding failure mode	es other than steel failure			
α _c [-]				1,5			
_oad-transfer facto	or			. -			
ΨΕV [-]							
$V_{Rk,s}$ see ETA-	12/0258:202	20					
$V_{Rk,c},V_{Rk,cp}$ see	e ETA-12/02	258:2020 o	r EN 1992-4:2018				
fischer Superb	ond dyna	mic					
Performance Essential charact Design method I	teristic unde according to	r shear fat o TR 061	igue load;			Annex C 2	

English translation prepared by DIBt



			nder tension and shear fation ng to TR061; zinc plated s	•	
Size			M12	M16	
Tension load					
Effective embedment depth	h _{ef,min}	[mm]	95	125	
Steel failure		'			
Characteristic steel fatigue resistance	ΔN _{Rk,s,0,∞}	[kN]	6,1	11,3	
Exponent for combined load	$\alpha s = \alpha sn$	[-]	0,5	0,7	
Characteristic fatigue resistand in uncracked and cracked cond		d failu	ure, concrete failure and pull ou	ıt,	
Characteristic bond $\Delta \tau_{Rk}$	_{p,ucr,0,∞} [N	mm²]	$ au_{ m Rk,ucr} \cdot 0.35$		
resistance	,p,cr,0,∞ [N	mm²]	TRk,cr •	0.35	
Concrete failure	,,,,,,,	1	Vitagei	,	
	ΔN _{Rk,c,0,∞}	[-]	0.5.Nr		
Characteristic concrete fatigue resistance			0,5 · N _{Rk,c} ¹)		
	ΔN _{Rk,sp,0,∞} [-]		0,5 · N _{Rk,sp} ¹⁾		
Exponent for combined load	αc	[-]	1,5		
Load-transfer factor	ΨFN	[-]	0,5		
Shear load					
Shear load capacity, steel failu	re without	lever a	arm		
Characteristic steel fatigue resistance	∆V _{Rk,s,0,∞}	[kN]	2,7	5,0	
Exponent for combined load	$\alpha_{\text{S}} = \alpha_{\text{SN}}$		0,5	0,7	
Concrete pryout failure					
Characteristic concrete fatigue resistance	/\ \/ \P\ 0 = 1		0,5 · V _{Rk,cp} 1)		
Concrete edge failure					
Characteristic concrete fatigue resistance	eristic concrete fatigue		0,5 · V _{Rk,c} 1)		
The value of h_{ef} (= l_{f}) under shear load	lf	[mm]	≥ 95	≥ 125	
Effective outside diameter of the anchor	d _{nom}	[mm]	12	16	
Exponent for combined load	$\alpha_{ extsf{c}}$		1,5		
Load-transfer factor	ΨFV	[-]	0,5	5	

 $^{^{1)}}$ N_{Rk,c}, N_{Rk,sp}, V_{Rk,c} and V_{Rk,cp} — Essential characteristics for concrete failure under static and quasi static load according to ETA-12/0258:2020 or EN 1992-4:2018.

fischer Superbond dynamic	
Performance	Annex C 3
Essential characteristics under tension / shear fatigue load;	
Design method II according to TR 061; zinc plated steel 8.8	

English translation prepared by DIBt



				and shear fati stainless ste	,	v class 70
Size			M12	M16	M20	M24
Tension load						
Effective embedment depth	h _{ef,min}	[mm]	95	125	170	220
Steel failure						
Characteristic steel fatigue resistance	ΔN _{Rk,s,0,∞}	[kN]	6,6	12,4	19,4	27,8
Exponent for combined load	$\alpha s = \alpha sn$	[-]	0,5 0,7			
Characteristic fatigue resistand in uncracked and cracked cond		ed failu	ure, concrete fa	ilure and pull o	ut,	
Characteristic bond $\Delta au_{ extsf{Rk},}$	p,ucr,0,∞ [N	/mm²]		τ _{Rk,ucr}	· 0,35	
resistance	,p,cr,0,∞ [N	/mm²]		TRk,cr	· 0,35	
Concrete failure	4, , , , -			·		
Characteristic concrete fatigue	ΔN _{Rk,c,0,∞}	[-]	0,5 · N _{Rk,c} 1)			
resistance	ΔN _{Rk,sp,0,∞}	[-]	0,5 · N _{Rk,sp} ¹⁾			
Exponent for combined load	<u> </u>		1,5			
Load-transfer factor	•		0,5			
Shear load		[-]				
Shear load capacity, steel failu	re without	lever a	arm			
Characteristic steel fatigue resistance	ΔV _{Rk,s,0,∞}	[kN]	3,6	6,6	10,3	14,9
Exponent for combined load	$\alpha_s = \alpha_{sn}$		0,5		0,7	
Concrete pryout failure						
Characteristic concrete fatigue resistance	ΔV _{Rk,cp,0,∞}	[kN]] 0,5 · V _{Rk,cp} 1)			
Concrete edge failure						
Characteristic concrete fatigue resistance	ΔV _{Rk,c,0,∞}	[kN]	0,5 · V _{Rk,c} 1)			
The value of h _{ef} (=l _f) under shear load	lf	[mm]	≥ 95	≥ 125	≥ 160	≥ 190
Effective outside diameter of the anchor	d _{nom}	[mm]	12	16	20	24
Exponent for combined load	ας		1,5			
Load-transfer factor	ΨFV	[-]		0,	5	

¹⁾ N_{Rk,c}, N_{Rk,sp}, V_{Rk,c} and V_{Rk,cp} − Essential characteristics for concrete failure under static and quasi static load according to ETA-12/0258:2020 or EN 1992-4:2018, for τ_{Rk} (M24-R-70) ≤ 0,85 · τ_{Rk} (M20-R-70)

fischer Superbond dynamic	
Performance	Annex C 4
Essential characteristics under tension / shear fatigue load;	
Design method II according to TR 061; stainless steel R property class 70	